

Discrete mathematics I

Graphs

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Based on Hungarian slides by Mérai László

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Basic concepts of graphs

Definition (graph (undirected))

A triple $G = (\varphi, E, V)$ is called an **(undirected) graph**, if E and V are sets such that $V \neq \emptyset$, $V \cap E = \emptyset$ and $\varphi: E \rightarrow \{\{v, v'\} \mid v, v' \in V\}$. E is called the **set of edges**, V is called the **set of vertices (nodes)** and φ is the **incidence function**. (The map φ assigns to each element of E an unordered pair of elements in V .)

Note: The graphs according to the above definition are often called **multigraphs**, because they can have so called parallel edges.

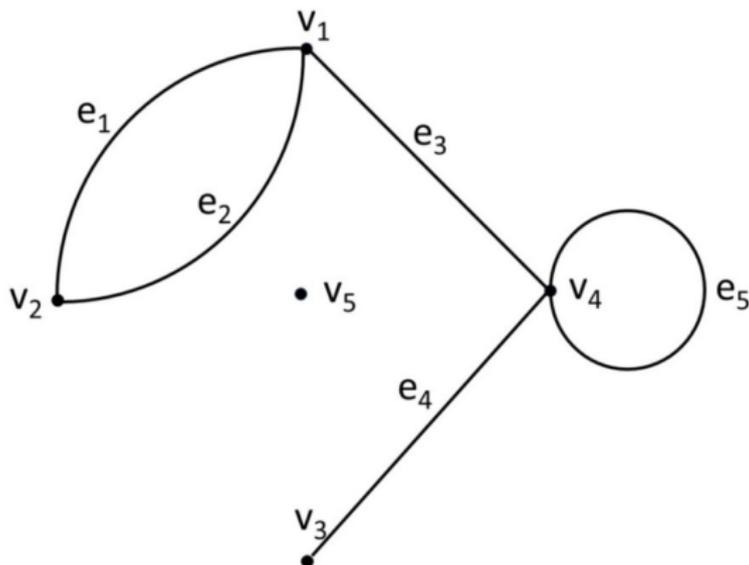
Definition (incidence of a vertex and an edge)

If $v \in \varphi(e)$ then we say that e is **incident to v** and v is **incident to e** , or – in other words – v is an **endpoint of e** .

Definition (incidence relation)

The incidence function determines the so called **incidence relation**
 $I \subseteq E \times V: (e, v) \in I \Leftrightarrow v \in \varphi(e)$.

Example



$$V = \{v_1, v_2, v_3, v_4, v_5\}$$

$$E = \{e_1, e_2, e_3, e_4, e_5\}$$

$$\varphi = \{(e_1, \{v_1, v_2\}), (e_2, \{v_1, v_2\}), (e_3, \{v_1, v_4\}), (e_4, \{v_3, v_4\}), (e_5, \{v_4\})\}$$

Basic concepts of graphs

Definition (loops, parallel edges, simple graphs)

If an edge is incident only to one vertex then we call this edge a **loop**.
If $e \neq e'$ and $\varphi(e) = \varphi(e')$ then e and e' are called **parallel edges**.
If a graph does not contain any loops nor any parallel edges, then this graph is called a **simple graph**.

Definition (finite graphs and empty graphs)

If E and V are both finite sets, then the graph is called a **finite graph**, otherwise it is an **infinite graph**.
If $E = \emptyset$ then the graph is called an **empty graph**.

Most graphs considered in informatics are finite, therefore in the rest of this course we are going to study finite graphs.

Basic concepts of graphs

Definition (incident edges, adjacent vertices)

The edges $e \neq e'$ are called **incident** (or in some sources **adjacent**), if there exists $v \in V$ such that $v \in \varphi(e)$ and $v \in \varphi(e')$. The vertices $v \neq v'$ are **adjacent**, if there exists $e \in E$ such that $v \in \varphi(e)$ and $v' \in \varphi(e)$.

Definition (degree of a vertex)

The **degree** of a vertex v is the number of edges incident to it, counting each loop twice. Notation: $d(v)$ or $\text{deg}(v)$.

Definition (isolated vertex)

If $d(v) = 0$ for some $v \in V$ then v is called an **isolated vertex**.

The sum of the degrees of all vertices in a graph

Theorem (Handshaking Theorem)

In any graph $G = (\varphi, E, V)$ we have:

$$\sum_{v \in V} d(v) = 2|E|.$$

Proof

Induction by the number of edges in the graph:

Base step: If $|E| = 0$ then the values on both sides of the equality are 0.

Inductive step: Assume that the statement is true when $|E| = n$, for some $n \in \mathbb{N}$. Let G be a graph with $n + 1$ edges. By deleting one edge of G we obtain a graph G' with n edges. By our inductive hypothesis, the statement is true for G' . If we now add to G' the edge deleted earlier from G , the values on both sides of the equality will increase by 2, hence the equality remains true. Therefore the statement also holds for G .

Basic concepts of graphs

Definition (deleting edges from a graph)

Let $G = (\varphi, E, V)$ be a graph and $E' \subseteq E$. The graph obtained by deleting the set of edges E' from G is the graph $G' = (\varphi|_{E \setminus E'}, E \setminus E', V)$.

Definition (deleting vertices from a graph)

Let $G = (\varphi, E, V)$ be a graph and $V' \subseteq V$. Denote by E' the set of those edges in E which are incident to at least one vertex in V' . The graph obtained by deleting the set of vertices V' from G is the graph $G' = (\varphi|_{E \setminus E'}, E \setminus E', V \setminus V')$.

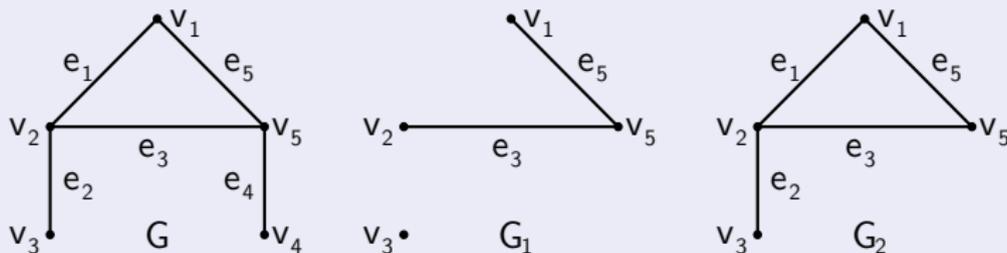
Basic concepts of graphs

Definition (subgraphs, supergraphs)

A graph $G' = (\varphi', E', V')$ is called a **subgraph** of a graph $G = (\varphi, E, V)$, if $E' \subseteq E$, $V' \subseteq V$ and $\varphi' \subseteq \varphi$. In this case we also say that G is a **supergraph** of G' .

If E' contains all those edges of G which have both endpoints in V' , then G' is called a **subgraph spanned** (or **induced**) by V' .

Example



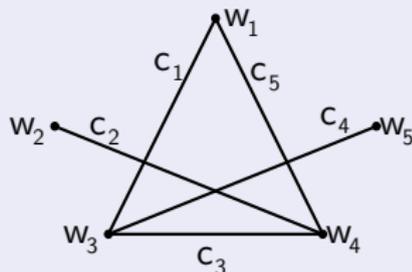
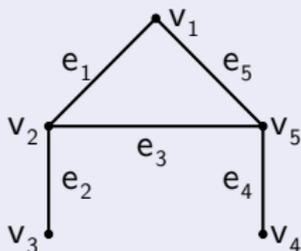
G_1 is a subgraph, but not a spanned subgraph of G and G_2 is a spanned subgraph of G .

Basic concepts of graphs

Definition (isomorphic graphs)

Two graphs $G = (\varphi, E, V)$ and $G' = (\varphi', E', V')$ are said to be **isomorphic** to each other, if there exist bijections $f: E \rightarrow E'$ and $g: V \rightarrow V'$ such that for every $e \in E$ and $v \in V$, e is incident to v if and only if $f(e)$ is incident to $g(v)$.

Example



Suitable bijections f and g :

$$f = \{(e_1, c_5), (e_2, c_2), (e_3, c_3), (e_4, c_4), (e_5, c_1)\}$$

$$g = \{(v_1, w_1), (v_2, w_4), (v_3, w_2), (v_4, w_5), (v_5, w_3)\}$$

Basic concepts of graphs

Definition (complete graphs)

A simple graph in which any two vertices are adjacent is called a **complete graph**. The complete graph with n ($n \in \mathbb{N}^+$) vertices is denoted by K_n .

Comment: It is easy to show that for any $n \in \mathbb{N}^+$, all complete graphs on n vertices are isomorphic, hence K_n is unique up to graph isomorphism.

Proposition (The number of edges in K_n)

For every $n \in \mathbb{N}^+$, K_n has $\binom{n}{2} = \frac{n(n-1)}{2}$ edges.

Definition (regular graphs)

If the degree of every vertex in a graph is equal to n for some $n \in \mathbb{N}$ then the graph is called **n -regular**. A graph is called **regular**, if it is n -regular for some $n \in \mathbb{N}$.

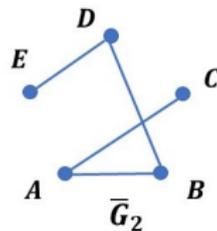
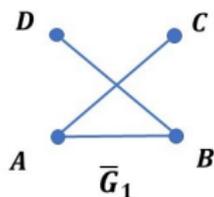
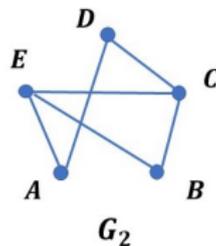
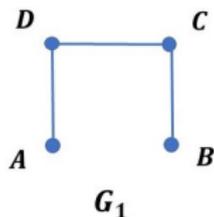
Comment: For any $n \in \mathbb{Z}$ K_n is $(n-1)$ -regular.

Complement of a graph

Definition (complement of a simple graph)

The **complement** of a simple graph G is the simple graph \overline{G} which has the same set of vertices as G and in which two (distinct) vertices are connected by an edge if and only if they are not connected in G .

Examples



Basic concepts of graphs

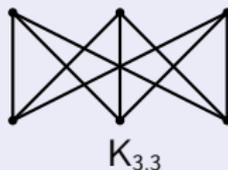
Definition (bipartite graphs)

A graph $G = (\varphi, E, V)$ **bipartite graph**, if V can be expressed as the union of two disjoint sets V' and V'' such that for every edge e in E one endpoint of e is in V' and the other endpoint of e is in V'' .

Definition (the graphs $K_{m,n}$)

Let $m, n \in \mathbb{N}^+$. The simple bipartite graph in which $|V'| = m$ and $|V''| = n$ and every vertex in V' is adjacent to every vertex in V'' , is denoted by $K_{m,n}$.

Example



Further special graphs

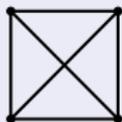
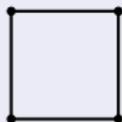
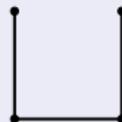
Definition (cycle graphs, path graphs, stars)

For every $n \in \mathbb{N}^+$ the **cycle graph** C_n on n vertices (or **n-cycle** or **n-gon**) is a simple graph with n vertices v_1, v_2, \dots, v_n and n edges e_1, e_2, \dots, e_n such that for every $1 \leq i \leq n-1$: $\varphi(e_i) = \{v_i, v_{i+1}\}$ and $\varphi(e_n) = \{v_n, v_1\}$.

For every $n \in \mathbb{N}$ the **path graph** P_n is the graph obtained by deleting one edge from the graph C_{n+1} .

For every $n \in \mathbb{N}^+$ the **star graph** S_n is the graph $K_{n,1}$. (S_0 can also be defined as a graph consisting of a single vertex and containing no edges.)

Examples

 K_4  C_4  P_3  S_4

Basic concepts of graphs

Definition (walk)

Let $G = (\varphi, E, V)$ be a graph, $n \in \mathbb{N}$. A **walk of length n** from vertex v_0 to v_n is a sequence

$$v_0, e_1, v_1, e_2, v_2, \dots, v_{n-1}, e_n, v_n$$

where

- $v_j \in V \quad 0 \leq j \leq n$,
- $e_k \in E \quad 1 \leq k \leq n$,
- $\varphi(e_m) = \{v_{m-1}, v_m\} \quad 1 \leq m \leq n$.

If $v_0 = v_n$, then the walk is a **closed walk**, otherwise it is an **open walk**.

Definition (trail/line)

If a walk does not contain repeated edges, then it is called a **trail** (or **line**). According to the above definition, a trail can be an **open trail** or a **closed trail**.

Basic concepts of graphs

Definition (path)

If a walk does not contain repeated vertices then it is called a **path**.

Comments

- Every path is also a trail.
- A walk of length **0** is also a path consisting of a single vertex.
- A walk of length **1** is a path if and only if the single edge contained by it is not a loop.

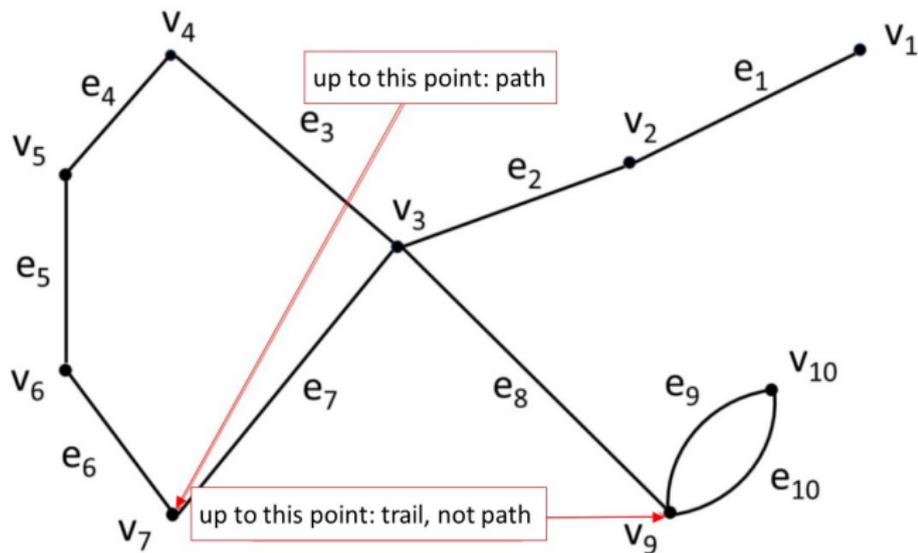
Definition (circuit)

A **circuit** is a closed trail of length ≥ 1 .

Definition (cycle)

A **cycle** is a circuit which contains no repeated vertices apart from the first and last vertices, which are identical.

Example



path: $v_1, e_1, v_2, e_2, v_3, \dots, v_6, e_6, v_7$;

line, but not a path: $v_1, e_1, v_2, e_2, v_3, e_3, v_4, \dots, e_7, v_3, e_8, v_9$;

cycle: $v_3, e_3, v_4, e_4, v_5, e_5, v_6, e_6, v_7, e_7, v_3$.

Basic concepts of graphs

Proposition (Creating a path from a walk)

Given any walk between two distinct vertices v and v' of a graph, we can obtain a path from v to v' by deleting suitable vertices and edges of the walk.

Proof

Consider the walk:

$$v = v_0, e_1, v_1, e_2, v_2, \dots, v_{n-1}, e_n, v_n = v'.$$

If this walk does not contain any repeated vertices, then it is already a path. Otherwise we have $v_i = v_j$ for some $i < j$. By deleting the part

$$e_{i+1}, v_{i+1}, e_{i+2}, v_{i+2}, \dots, v_{j-1}, e_j, v_j$$

from the walk we obtain a shorter walk from v to v' . Repeat this step until there are no repeated vertices in the walk. The process will finish in finite number of steps, since the length of the walk reduces in each step. When the process stops there are no repeated vertices, hence we obtained a path.

Basic concepts of graphs

Definition (connected graphs)

A graph is said to be **connected** if there is a walk (or, equivalently, there is a path) between any pair of vertices of the graph.

For a graph $G = (\varphi, E, V)$ define the relation \sim on V : let $v \sim v'$ if and only if there exists a walk (or, equivalently, there is a path) from v to v' in G .

Since \sim is an equivalence relation (Why?), the set of corresponding equivalence classes will be a partition of V .

Definition (components of a graph)

The subgraphs spanned by these equivalence classes are called the **components** of the graph.

Comment

A graph is connected if and only if it consists of only one component.

Trees

Definition (tree)

A graph is called a **tree** if it is connected and contains no cycle (in other words: it is an acyclic graph).

Theorem (Equivalent characterisations of trees 1.)

For a simple graph G the following conditions are equivalent:

- ① G is a tree;
- ② G is connected, and by deleting any of its edges, the remaining subgraph is not connected (i.e. G is a minimally connected graph);
- ③ any vertices v and v' in G there is exactly one path from v to v' ;
- ④ G contains no cycles, but by adding any new edge to G , the new graph will contain a cycle (i.e. G is a maximally acyclic graph).

Structure of the proof

(1) \Rightarrow (2) \Rightarrow (3) \Rightarrow (4) \Rightarrow (1)

Trees

Proof

(1) \Rightarrow (2)

By the definition of a tree, G is connected. The other part of the statement we show by proof by contradiction. Suppose there is an edge e (denote its endpoints by v and w) in the graph such that after deleting e the remaining subgraph is connected. Then in the remaining subgraph there is a path from v to w : $v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = w$. Adding e and v to this path we obtain a cycle in G : $v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = w, e, v$.

(2) \Rightarrow (3)

Let v and w be vertices in G . Since G is connected, there is at least one path from v to w . We show that there cannot exist two different paths from v to w , by proof by contradiction: Suppose there exist 2 different paths from v to w :

$v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = w$ and

$v = v_0, e'_1, v'_1, e'_2, \dots, v'_{m-1}, e'_m, v'_m = w$. Let k be the smallest index such that $v_k \neq v'_k$. (Why does such a k exist?) By deleting the edge e_k from G we obtain a connected subgraph, because the walk v_{k-1}, e_k, v_k can be replaced by the walk $v_{k-1}, e'_k, v'_k, \dots, e'_m, v'_m = w, e_n, v_{n-1}, e_{n-1}, v_{n-2}, \dots, v_{k+1}, e_{k+1}, v_k$. \nexists

Trees

Proof

(3) \Rightarrow (4)

We show that G contains no cycle, by proof by contradiction: Suppose there is a cycle $v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = v$. Then there exist two different paths from v_1 to v : $v_1, e_2, \dots, v_{n-1}, e_n, v_n = v$ and $v_1, e_1, v_0 = v$. \nexists

Showing that G is maximally acyclic: If the newly added edge e is a loop and v is its endpoint, then v, e, v is a cycle. Otherwise e has two distinct endpoints v and w . Let $v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = w$ be the path from v to w in G . By adding the edge e and vertex v to this path we obtain the cycle: $v = v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n = w, e, v$.

(4) \Rightarrow (1)

By our assumption in (4), G contains no cycle. It remains to show that G is connected, i.e. for any vertices v and w there is a path in G . Add an edge e with endpoints v and w to the graph. The resulting new graph will contain a cycle with the edge e in it (Why?):

$w, e, v, e_1, v_1, e_2, \dots, v_{n-1}, e_n, w$. Then $v, e_1, v_1, e_2, \dots, v_{n-1}, e_n, w$ is a path from v to w .

Trees

Lemma (Vertices of degree 1 in finite acyclic graphs)

If a finite graph G does not contain a cycle and contains at least one edge then there are at least 2 vertices with degree 1 in G .

Proof

Since G is finite, among all paths in G there is at least one path P of maximal length (i.e. a path P such that there is no path longer than P in G). Let P be: $v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n$. As G contains at least one edge, the length of P is at least 1, hence $v_0 \neq v_n$.

We show that $\deg(v_0) = \deg(v_n) = 1$. Proof by contradiction: Suppose that there is an edge $e \neq e_1$ which is incident to v_0 . Then the other endpoint v_0 of e must lie on P , because otherwise

$v_0, e, v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n$ would be a path longer than P , a contradiction. Hence $v_0 = v_k$ for some vertex v_k on P . Then

$v_k, e, v_0, e_1, v_1, e_2, \dots, v_{k-1}, e_k, v_k$ is a cycle, which is also a contradiction. Therefore there is no edge $e \neq e_1$ incident to v_0 and so $\deg(v_0) = 1$. Similarly $\deg(v_n) = 1$.

Trees

Theorem (Equivalent characterisations of trees 2 - using the number of edges)

For a simple graph G on n vertices ($n \in \mathbb{N}^+$) the following conditions are equivalent:

- ① G is a tree;
- ② G contains no cycles (i.e. acyclic) and it has $n - 1$ edges;
- ③ G is connected and it has $n - 1$ edges.

Proof

If $n = 1$ then the statement is clearly true. (Why?)

(1) \Rightarrow (2): Proof by induction on n : Suppose the statement is true for some $n \in \mathbb{N}^+$.

Let G be a tree with $n + 1$ vertices. Then G has a vertex v of degree 1. (Why?)

Delete vertex v from G . The new graph G' is clearly acyclic. It is also connected: since v can be contained only as an endpoint in any path in G , hence for any vertices v' and v'' in G' , the path between v' and v'' in G cannot contain v , and so it is also a path in G' . Therefore G' is connected, hence a tree, and so by our inductive hypothesis it has $n - 1$ edges, and so G has n edges.

Trees

Proof

(2) \Rightarrow (3): Proof by induction on n : Suppose the statement is true for some $n \in \mathbb{N}^+$. Let G be an acyclic graph with $n + 1$ vertices and n edges. It is sufficient to show that G is connected. The graph G contains a vertex v of degree 1. (Why?) Delete v from G . The resulting graph G' is also acyclic and has n vertices and $n - 1$ edges. Hence, by our inductive hypothesis G' is connected. Between any vertices v' and v'' in G' there is a path in G' , which is also a path in G . From any vertex v' in G' we can obtain a path in G to v if we consider the path in G' from v' to the vertex adjacent to v in G and to this path we add the edge incident to v , and v .

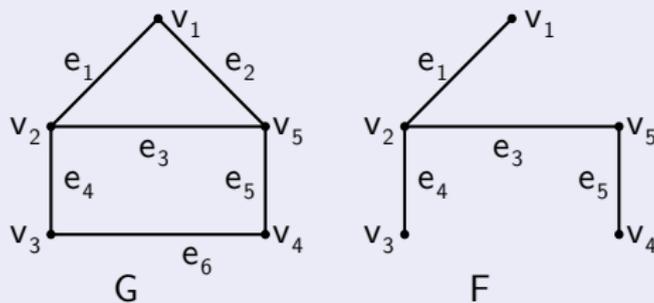
(3) \Rightarrow (1): Let G be a graph satisfying Condition (3). It is sufficient to show that G is acyclic. Proof by contradiction: Suppose G contains a cycle. Then by deleting any edge of a cycle in G we obtain a connected graph. (Why?) Repeat this step, while the graph still has a cycle. The process halts after finite steps (Why?), when the new graph T is a tree. If we omitted $k > 0$ edges during the process, then T has $n - 1 - k < n - 1$ edges. Because of the implication (1) \Rightarrow (2), T has $n - 1$ edges, a contradiction. \neq

Spanning trees

Definition (spanning tree)

A subgraph T of a graph G is called a **spanning tree** of G , if T is a tree and T contains all vertices of G .

Example



Spanning tree

Proposition (Existence of a spanning tree)

Every finite connected graph has a spanning tree.

Proof

Let G be a finite, connected graph. If G contains a cycle then delete an edge from one of the cycles in G . The new graph is still connected. (Why?) Repeat this step until the graph becomes acyclic. This process will terminate in finite number of steps, since the number of edges in the graph decreases in each step. When the process stops, the graph obtained is a spanning tree of G .

Spanning tree

Proposition (A lower bound on the number of cycles)

A finite connected graph $G = (\varphi, E, V)$ contains at least $|E| - |V| + 1$ cycles with pairwise different sets of edges.

Proof

Let T be a spanning tree of G . Then T has $|V| - 1$ edges. Denote by E' the set of those edges in G which are not in T . If we add any edge $e \in E'$ to T there will be a cycle K_e in the new graph F' (Because T is a maximally acyclic graph), which is also a cycle in G . The cycle K_e contains the edge e (Why?) and if $e \neq e' \in E'$ then $K_{e'}$ does not contain e . This way we obtain $|E'| = |E| - |V| + 1$ cycles with pairwise different sets of edges.

Comment

The above lower bound does not necessarily give the exact number of cycles in the graph ($3 > 7 - 6 + 1 = 2$).



Forests, spanning forests

Definition (forest, spanning forest)

An acyclic graph is called a **forest**.

A subgraph F of a graph G containing one spanning tree from each component of G is called a **spanning forest** of G .

Proposition (Spanning forests in finite graphs)

Every finite graph has a spanning forest.

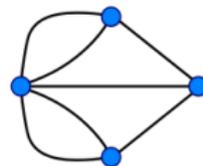
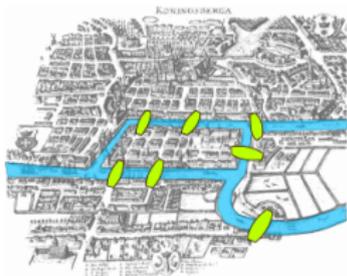
Proposition (Number of edges in a finite forest)

The number of edges in a finite forest F equals the number of vertices in F minus the number of components in F .

Comment

Among all (not necessarily connected) graphs, forests and spanning forests play a similar role to those of trees and spanning trees among connected graphs.

Euler trail



Definition (Euler trail)

A trail that contains all edges of a graph is called an **Euler trail**. (An Euler trail can be an **open Euler trail** or a **closed Euler trail**, depending on whether it is an open or a closed trail.)

Comment

Since a trail does not contain repeated edges, an Euler trail contains every edge of the graph exactly once.

Euler trail

Theorem (Existence of a closed Euler trail)

A finite connected graph contains a closed Euler trail if and only if the degree of every vertex in the graph is even.

Proof

\Rightarrow : Let $v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_0$ be a closed Euler trail in the graph. Following the Euler trail we 'enter' each vertex v the same number of times as we 'leave' it. Hence the trail contains an even number of edges incident to any vertex v (counting loops twice), and so the degree of every vertex is even.

Euler trail

Proof

⇐: *The proof is constructive. First consider an arbitrary closed trail (a closed trail certainly exists in any graph, for example a trail containing no edges, just a single vertex), call it T . As any closed trail, T contains an even number of edges incident to any vertex of the graph (counting each loop twice). (Why?)*

If the current closed trail T does not contain all edges of the graph, then – because the graph is connected – there is a vertex w in our closed trail, which has incident edges not included in T . Start a new trail T' from w leaving w on an edge not used in T and proceed always on unused edges. As every vertex has an even number of edges not used in T , we can only get stuck when returning to w . Consider the following new trail: starting at w move along T , then after arriving back at w at the end, move along T' , at the end of which arriving back at w . This way we obtain a closed trail longer than T . Hence, by repeating this expansion step, after a finite number of expansions we obtain a closed Euler trail.

Hamiltonian path, Hamiltonian cycle

Definition (Hamiltonian path)

If a path in a graph contains all vertices of the graph then we call it a **Hamiltonian path**.

Comment

Since a path does not contain repeated vertices, a Hamiltonian path contains each vertex of the graph exactly once.

Definition (Hamiltonian cycle, Hamiltonian graph)

A **Hamiltonian cycle** in a graph is a cycle that contains all vertices of the graph. A graph is called a **Hamiltonian graph** if it contains a Hamiltonian cycle.

Theorem (Dirac, NP)

If in a simple graph $G = (\varphi, E, V)$, $|V| > 2$, and the degree of every vertex is at least $|V|/2$, then the graph contains a Hamiltonian cycle.

Planar graphs

Definition (planar graph)

A graph G is called a **planar graph**, if it can be drawn in (with a more technical word 'embedded in') the plane (\mathbb{R}^2) in such a way that its edges intersect only at their endpoints. (In other words, it can be drawn on the plane in such a way that no edges cross each other, except for at the vertices.) Such a drawing is called a **plane graph representation** or **planar embedding** of the graph.

Comment

Not all graphs are planar, i.e. not all graphs can be embedded into \mathbb{R}^2 (not even all finite graphs are planar). However every finite graph can be embedded into \mathbb{R}^3 .

Planar graphs

Definition (faces in a planar representation)

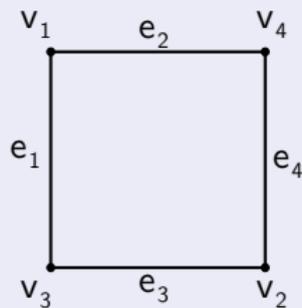
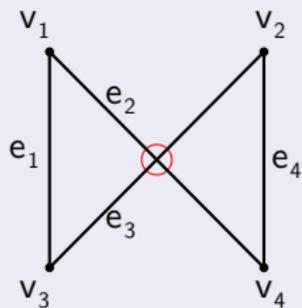
Given a planar embedding of a graph G , a **face** is a region – i.e. connected subset – of the plane surrounded by edges of G , (i.e. a face is a set of points, such that between any two points of a face, there is a line (curve) in the plane, such that it does not cross any of the edges (or vertices) of G). A face can be unbounded, and in that case it is an **external face**, otherwise it is an **internal face**.

Comment

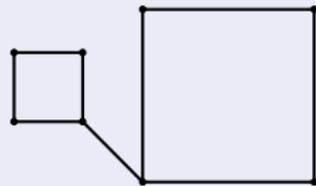
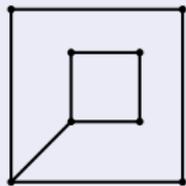
The status of internal/external face is not significant: An external face can become an internal face in a different planar embedding. However, the number of faces is independent from the embedding.

Planar graphs

Example



Example



Planar graphs

Theorem (Euler's formula)

Let $G = (\varphi, E, V)$ be a connected planar graph. Then for any planar embedding of G :

$$|E| + 2 = |V| + f$$

where f denotes the number of faces in the planar embedding.

Proof

Suppose there is a cycle in G . By deleting an edge of the cycle, two faces are merged, so both f and $|E|$ is reduced by 1. In the end, we obtain a tree for which the equation holds (Why?).

Planar graphs

Proposition (Upper bound on the number of edges in simple planar graphs)

For any simple, connected, planar graph $G = (\varphi, E, V)$ with $|V| \geq 3$: $|E| \leq 3|V| - 6$.

Proof

In case $|V| = 3$ there are two such graphs: P_2 and C_3 , both of which satisfy the inequality.

Assume $|V| > 3$. Then $|E| \geq 3$ (Why?). Since G is simple, every face is surrounded by at least 3 edges. Therefore if we count the number of edges surrounding each face and then add up these numbers for all faces then the sum obtained will be $\geq 3f$. As every edge separates at most two regions, in this sum every edge was counted at most twice, hence this sum is $\leq 2|E|$. Therefore $2|E| \geq 3f$. Expressing f from Euler's formula and substituting for it we obtain $2|E| \geq 3(|E| + 2 - |V|)$, which after rearrangement yields $|E| \leq 3|V| - 6$.

Comment

The theorem holds for disconnected graphs as well, since it can be made a connected planar graph by adding edges.

Planar graphs

Proposition (Lower bound on the minimal degree in simple planar graphs)

If $G = (\varphi, E, V)$ is a simple planar graph, then

$$\delta = \min_{v \in V} d(v) \leq 5.$$

Proof

We can assume $|V| \geq 3$ (Why?).

Proof by contradiction: Suppose $\delta \geq 6$. Then $6|V| \leq 2|E|$ (Why?), furthermore, using our previous theorem, $2|E| \leq 6|V| - 12$, implying $6|V| \leq 6|V| - 12$, a contradiction.

Comment

There exists 5-regular simple planar graph.

Planar graphs

Proposition

$K_{3,3}$ is not a planar graph.

Proof

Proof by contradiction: Suppose that on the contrary, $K_{3,3}$ is a planar graph. Denote by f the number of faces in its planar embeddings. Since $|E| = 9$ and $|V| = 6$, by Euler's formula $f = 5$ must hold. Since it is a simple bipartite graph, each face is surrounded by at least 4 edges (Why?), and every edge separates at most 2 faces, so $4f \leq 2|E|$, implying $20 \leq 18$, a contradiction.

Proposition

K_5 is not a planar graph.

Proof

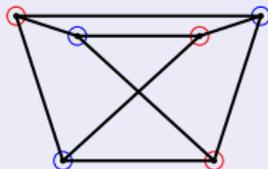
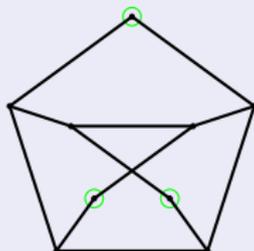
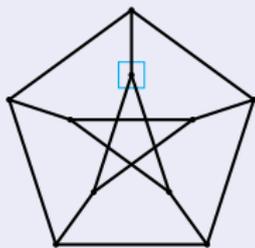
Proof by contradiction: Suppose that on the contrary, K_5 is a planar graph. Since $|E| = 10$ and $|V| = 5$, by the theorem about the upper bound on the number of edges in simple planar graphs $10 \leq 3 \cdot 5 - 6 = 9$, a contradiction.

Planar graphs

Definition (topological isomorphism of graphs)

The finite graphs G and G' are **topologically isomorphic** if they can be converted into each other applying the following transformation or its inverse a finite number of times: delete a vertex with degree two and connect its neighboring vertices with an edge.

Example



Theorem (Kuratowski (NP))

A simple and finite graph is a planar graph if and only if it has no subgraph topologically isomorphic to K_5 or $K_{3,3}$.

Labelled graphs

Definition

Let $G = (\varphi, E, V)$ be a graph, C_e and C_v be sets and $c_e: E \rightarrow C_e$ and $c_v: V \rightarrow C_v$ be functions. Then $(\varphi, E, V, c_e, C_e, c_v, C_v)$ is called a **labelled graph**, C_e the **set of edge labels**, C_v the **set of vertex labels**, $c_e: E \rightarrow C_e$ **edge labelling** and $c_v: V \rightarrow C_v$ **vertex labelling**.

Definition (edge labelled and vertex labelled graphs)

If only the set of edge labels and the edge labelling, or only the set of vertex labels and the vertex labelling are given then we talk about an **edge labelled** or **vertex labelled** graph, respectively.

Note

Labelled graphs are also called **coloured graphs**.

Labelled graphs

Definition (edge weighted and vertex weighted graphs)

If in a labelled graph $C_e = \mathbb{R}$ or $C_v = \mathbb{R}$ we talk about **edge weighting** and **edge weighted graph**, and **vertex weighting** and **vertex weighted graph**, respectively, and C_e and C_v respectively, is omitted from the notation.

Definition

Egy $G = (\varphi, E, V, w)$ edge weighted graph the weight **weight of a set of edges** $E' \subseteq E$ is $\sum_{e \in E'} w(e)$.

Theorem (Kruskal's algorithm)

Given an edge weighted graph G Kruskal's algorithm finds a minimum weight spanning forest of G .

- 1 Let F be the empty subgraph of G containing all vertices of G .
- 2 In each step the algorithm adds a new edge e of G to F with the following property (if such an edge e exists): by adding e to F no cycle is created in F and e has minimal weight among all edges of G not in F with this property.
- 3 If there does not exist any edge e in G not in F such that by adding e to F no cycle is created, the algorithm stops.

Labelled graphs

Theorem (Kruskal's algorithm)

Given an edge weighted graph G Kruskal's algorithm finds a minimum weight spanning forest of G .

Proof

Later...

Definition (greedy algorithm)

An algorithm is called a **greedy algorithm** if in each step it chooses the option which appears to be the most favourable in the given step (no forward thinking').

Note

Kruskal's algorithm is a greedy algorithm.

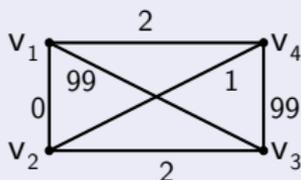
Labelled graphs

Note

A greedy algorithm does not always find an optimal solution to a problem.

Example

Find a minimum-weight Hamiltonian cycle in the following graph:



Directed graphs

Definition (directed graph)

A triple $G = (\psi, E, V)$ is called a **directed graph** (or **digraph**), where E and V are sets such that $V \neq \emptyset$, $V \cap E = \emptyset$ and $\psi: E \rightarrow V \times V$.

E is called the **set of edges**, V is the **set of vertices (points)** and ψ is the **incidence function**. Function ψ assigns to each element of E an ordered pair of vertices.

Terminology

If $\psi(e) = (v, v')$ v is the **starting point** and v' is the **endpoint** of e .

Definition (orientation of an undirected graph)

For any directed graph $G = (\psi, E, V)$ an undirected graph

$G' = (\varphi, E, V)$ can be obtained in the following way: for every edge e if $\psi(e) = (v, v')$ then define $\varphi(e)$ as $\{v, v'\}$. Then G is called an **orientation of G'** .

Directed graphs

Definition (strictly parallel edges)

If for some edges $e \neq e'$ we have $\psi(e) = \psi(e')$ then e and e' are said to be **strictly parallel edges**.

Definition (outdegree and indegree of a vertex)

The number of edges with starting point v is called the **outdegree of v** , denoted by $\text{deg}^+(v)$ or $d^+(v)$.

The number of edges with endpoint v is called the **indegree of v** denoted by $\text{deg}^-(v)$ or $d^-(v)$.

If $\text{deg}^+(v) = 0$ then v is called a **sink**; $\text{deg}^-(v) = 0$ then v is called a **source**.

Directed graphs

Theorem (Handshaking Theorem for Directed Graphs)

In any directed graph $G = (\psi, E, V)$:

$$\sum_{v \in V} d^+(v) = \sum_{v \in V} d^-(v) = |E|.$$

Definition (isomorphism of directed graphs)

The directed graphs $G = (\psi, E, V)$ and $G' = (\psi', E', V')$ are said to be **isomorphic**, if there exist bijections $f: E \rightarrow E'$ and $g: V \rightarrow V'$ such that for every $e \in E$ and $v \in V$: v is a starting point of e if and only if $g(v)$ is a starting point of $f(e)$ and v is an endpoint of e if and only if $g(v)$ is an endpoint of $f(e)$.

Directed graphs

Definition (directed subgraphs and supergraphs)

Let $G' = (\psi', E', V')$ and $G = (\psi, E, V)$ be directed graphs. G' is called a **directed subgraph of G** if $E' \subseteq E$, $V' \subseteq V$ and $\psi' \subseteq \psi$. Then G is a **directed supergraph of G'** .

If the directed subgraph G' contains all edges of G with starting- and endpoints both lying in V' then G' is called the **directed subgraph of G spanned (or induced) by V'** .