



# DEEPLY PROGRAMMABLE NETWORKS

SEPTEMBER 2020 – JUNE 2021

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PROGRAM  
FINANCED FROM  
THE NRCI FUND

# Paradigm shift in networking - 1



- Closed and proprietary HW and SW
- Implementing 100s of protocols
- Power hungry



- Whitebox switches  
+ Servers running the CP
- Merchant silicon
- Linux-based
- Open source

Networks are hard to manage  
Unreliable, hard to secure  
Hard to scale and extend  
**Slow innovation**

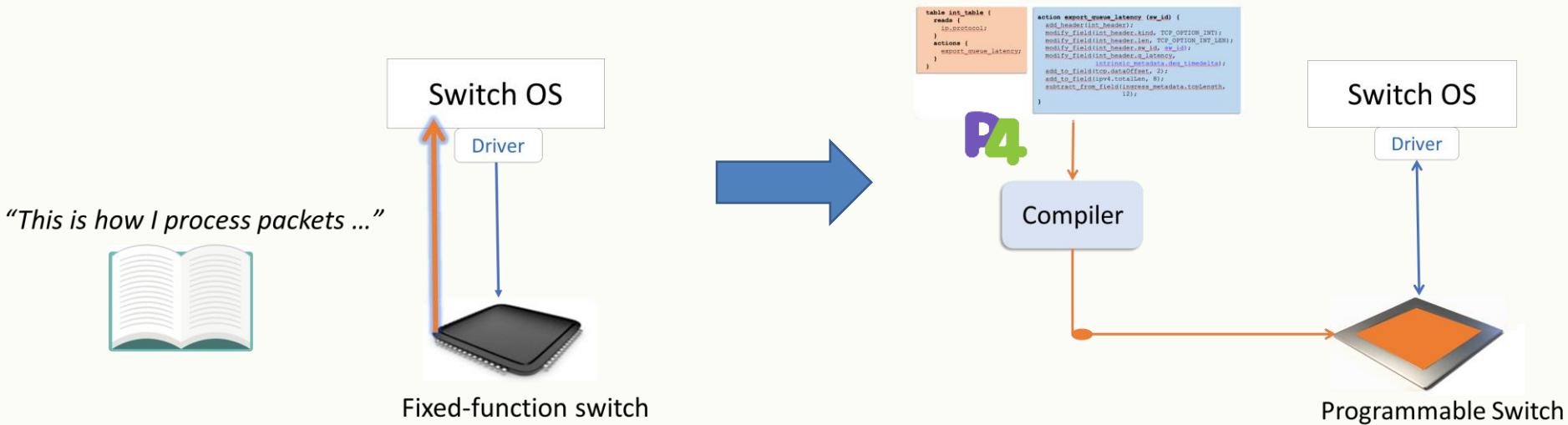
Easier to fix  
New features can be added  

- Traffic engineering
- Failure handling
- Security

**Faster innovation**

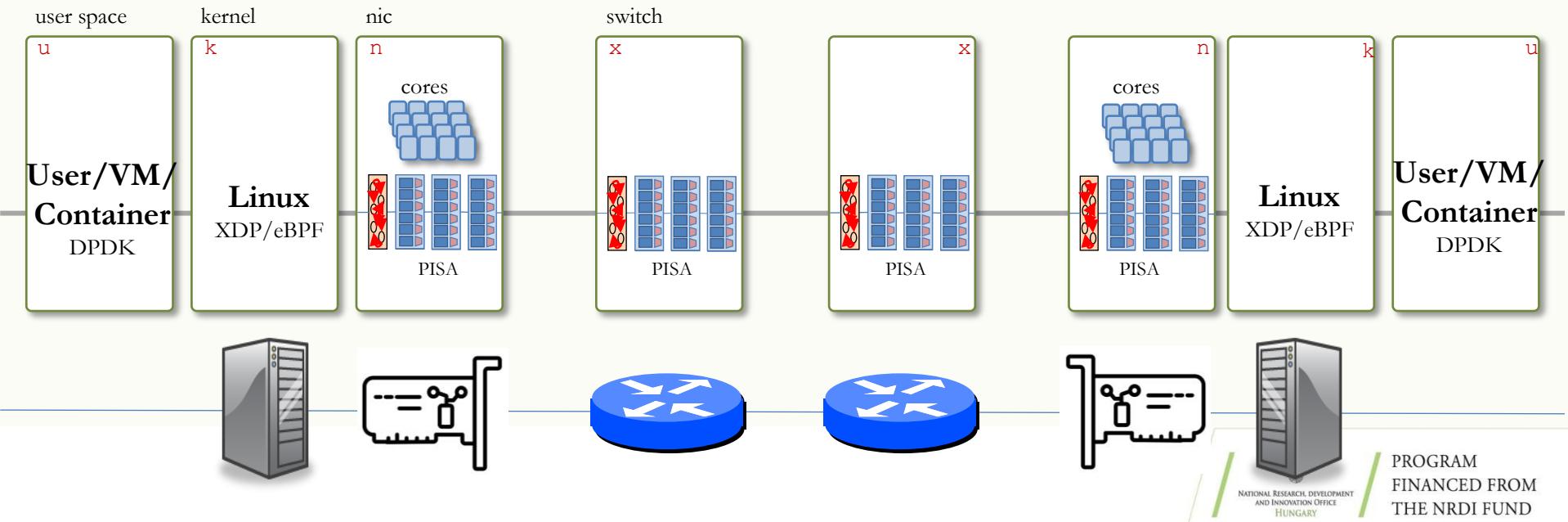
# Paradigm shift in networking - 2

*"This is precisely how you must process packets"*

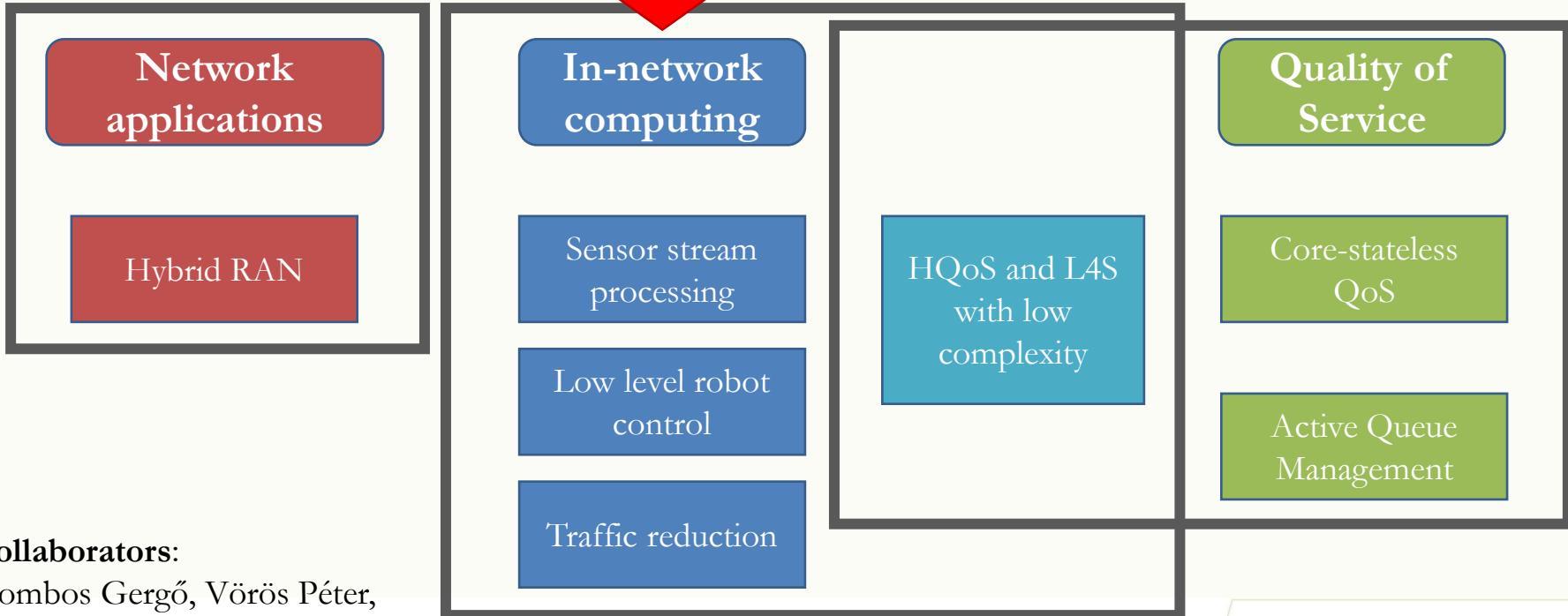
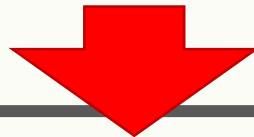


# Network as a programmable platform

- Programmable elements (e.g., in P4) at any point of the e2e path



September 2020 – June 2021



**Collaborators:**

Gombos Gergő, Vörös Péter,  
Szalai-Gindl János, Tejfel Máté,  
Tóthmérész Lilla, Király Tamás



# In-network computing



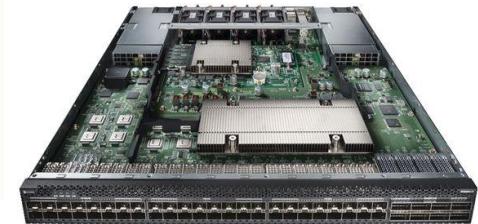
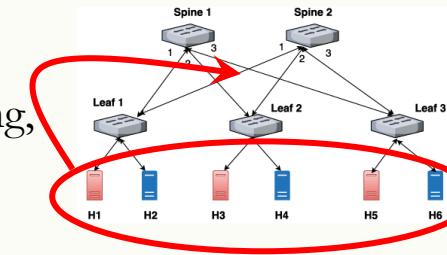
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# Why in-network computing?

- **Emerging field** of networking
  - With the advent of programmable switches (BF/Intel Tofino) and P4 language

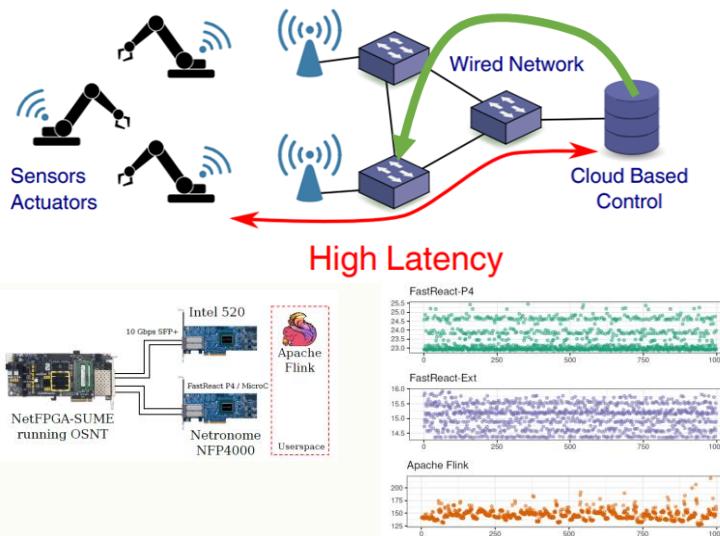


- Idea of **moving computations** from servers **to the network**
  - Enabling novel applications: caching, stream processing, query processing, load balancing, real-time control, in-network consensus, etc.
- Programmable switches are **not only** packet forwarding elements
  - Unexploited computational capacities
  - High throughput, ultra-low latency
  - Limitations
    - pipeline computing model, limited number of stages, limited memory, ...



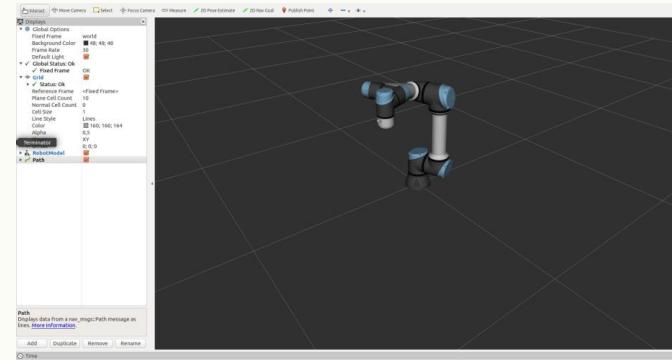
# Two recent results

## In-network event detection in sensor streams



IEEE TNSM – March 2021 (Q1/D1 journal)  
Joint work with Andreas Kasslerrel (KAU)

## In-network robot control



Accepted @ USENIX NSDI'22 (15-16% acceptance rate)  
Joint work with Ericsson Research.

nsdi'22

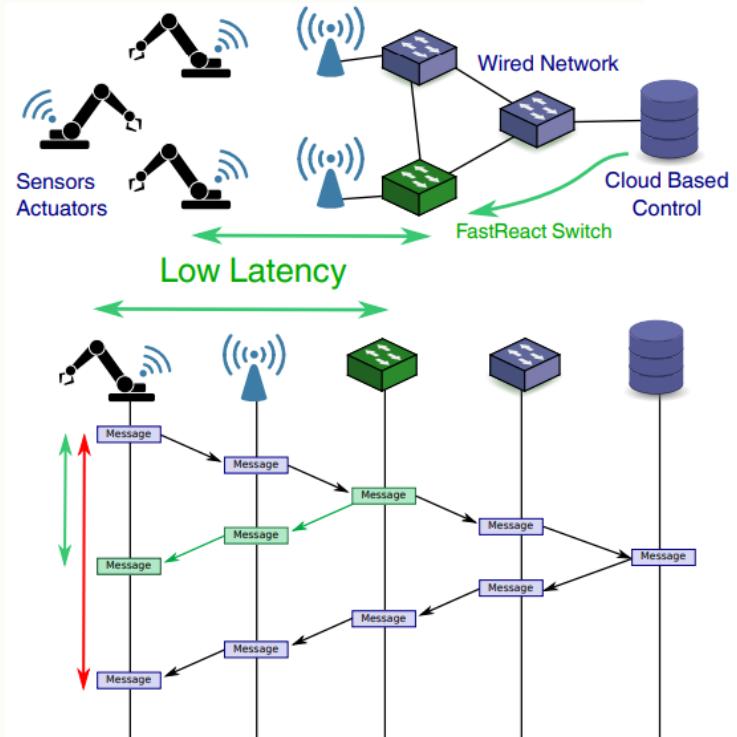
19th USENIX Symposium on Networked Systems Design and Implementation

# In-network event detection with FastReact\*



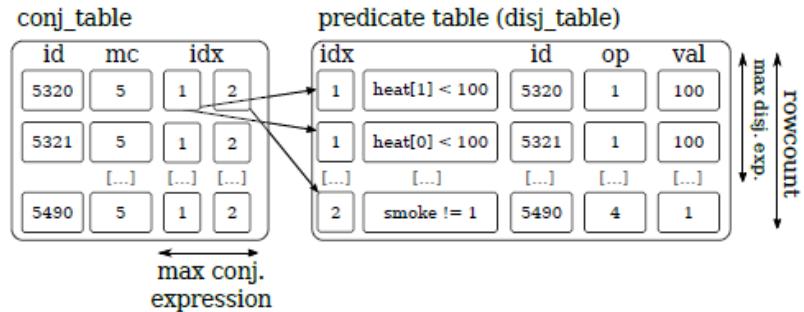
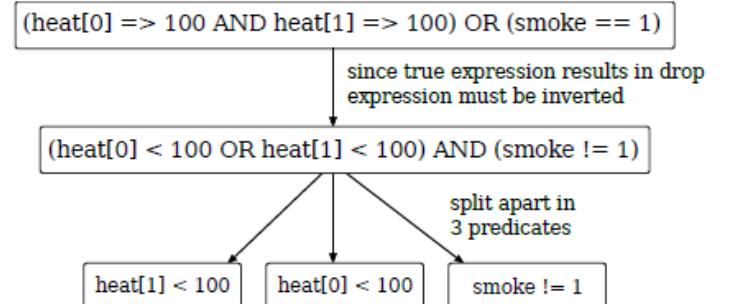
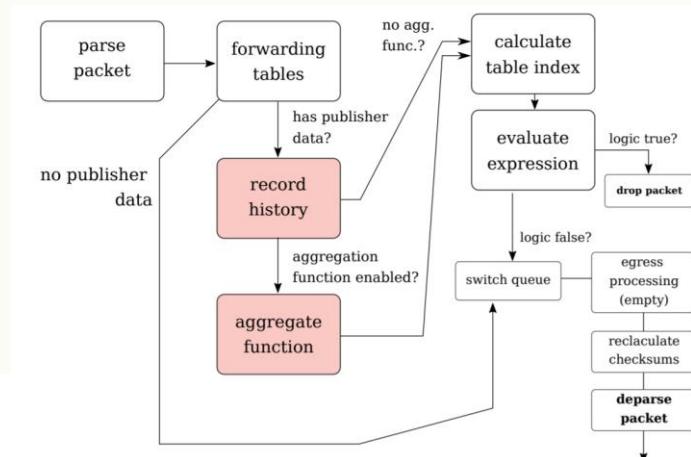
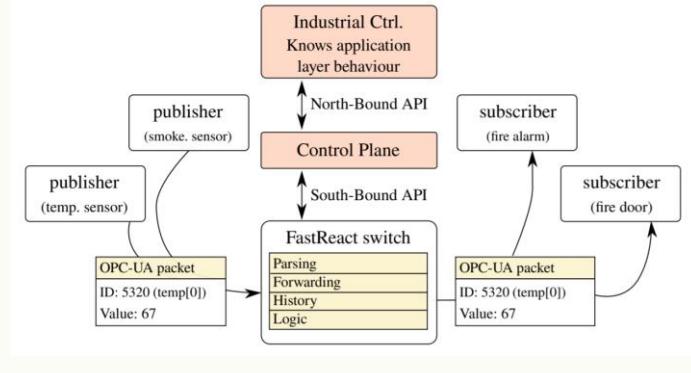
- **Local Decision Making** instead of centralized control
  - Early reaction reduces time required for processing
  - Reduces network data rate
  - Fewer devices that can fail
- **FastReact**
  - Implemented in P4 data plane programming language
  - Reconfigurable rules in runtime using BNF
  - Trigger local actions based on locally stored data

```
if (sensor1 > 50) && (sensor2 < 25):
    trigger_actuator(<portno>)
```



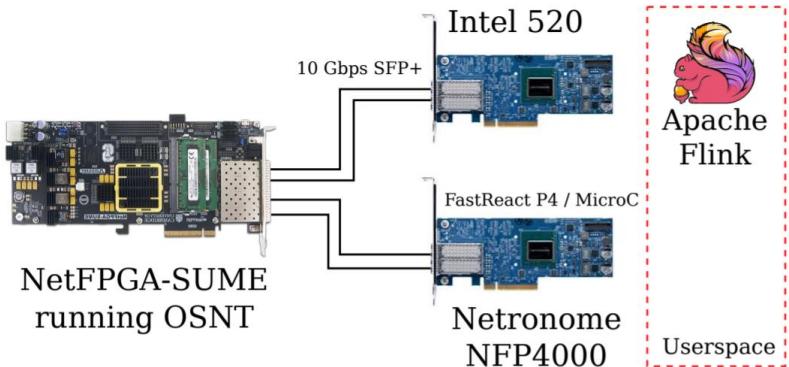
\* J. Vestin, A. Kassler, S. Laki, G. Pongrácz: *Towards In-Network Event detection and Filtering for Publish/Subscribe Communication using Programmable Data Planes*, In IEEE Transactions on Network and Service Management (IEEE TNSM), Volume: 18, Issue: 1, Page(s): 415 - 428, March 2021

# In-Network Event Detection and Filtering for Publish/Subscribe Communication

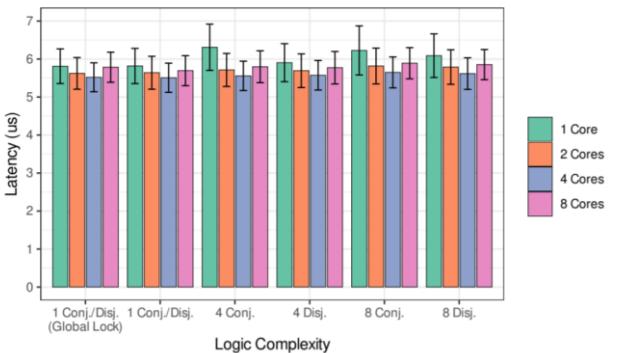


**Fig. 3:** FastReact table processing for the expression  $(heat[0] \geq 100 \wedge heat[1] \geq 100) \vee (smoke = 1)$ .

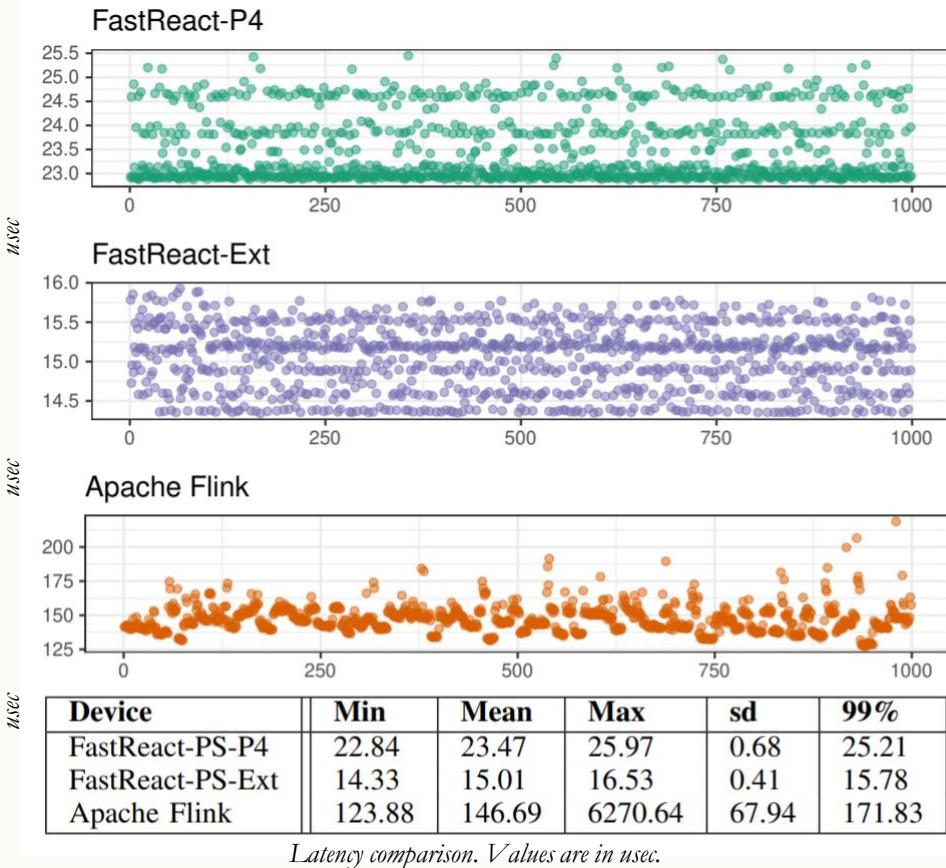
# Evaluation - Latency



**Fig. 5:** Testbed setup used for evaluation

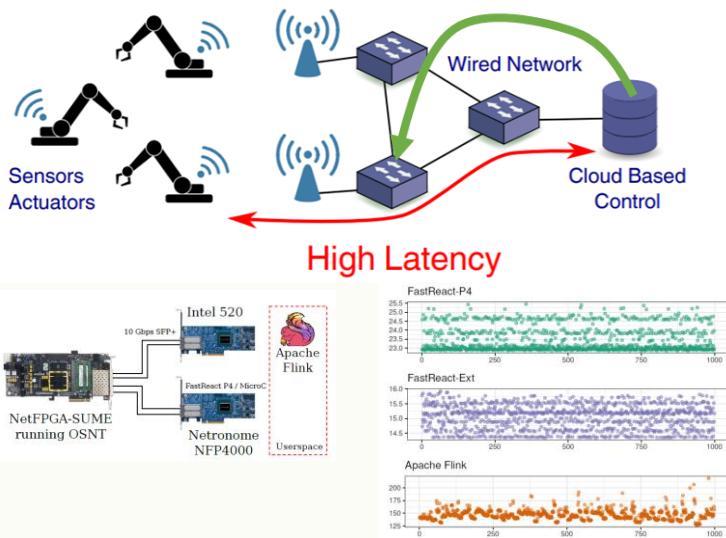


**Fig. 14:** Latency measurements of FastReact-PS-P4 running on the T4P4S switch, varying the disjunctive and conjunctive logic complexity. Low throughput case, preventing queue buildup.



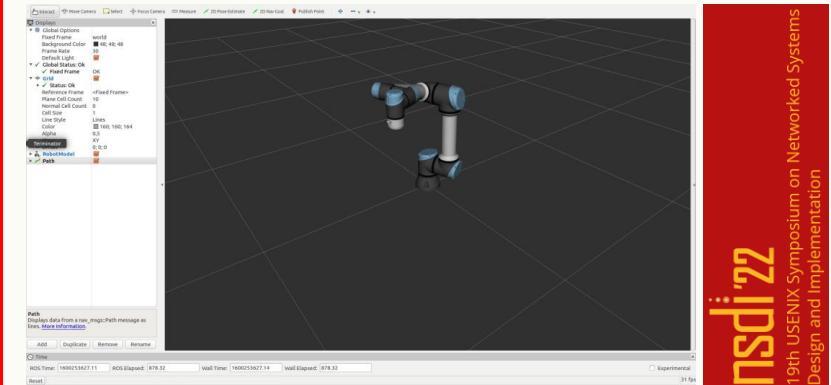
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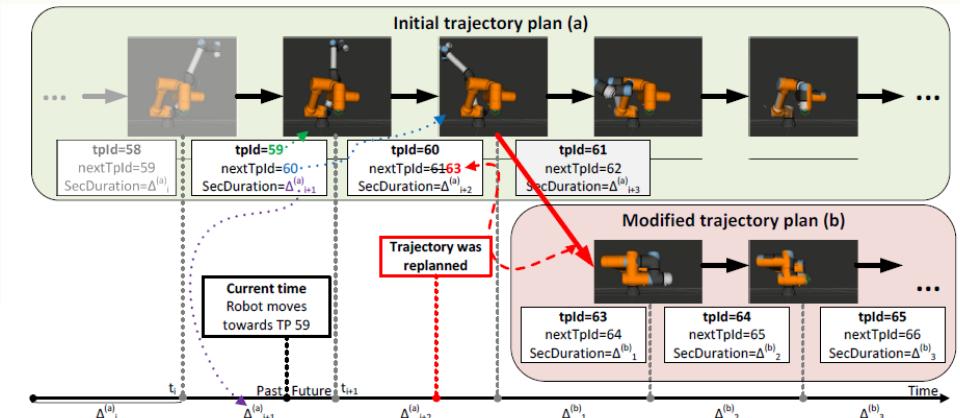
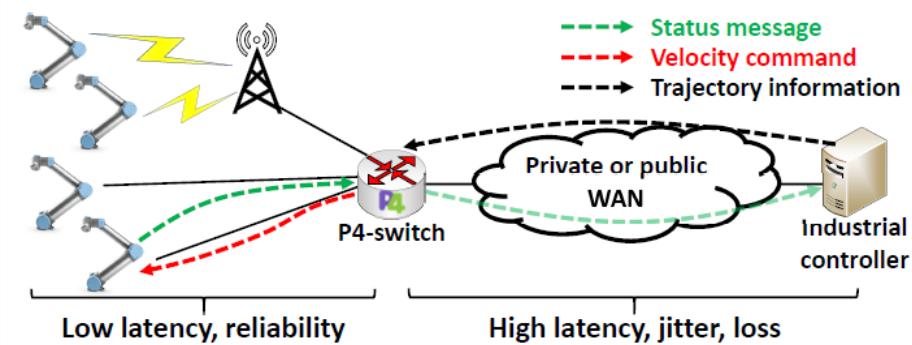
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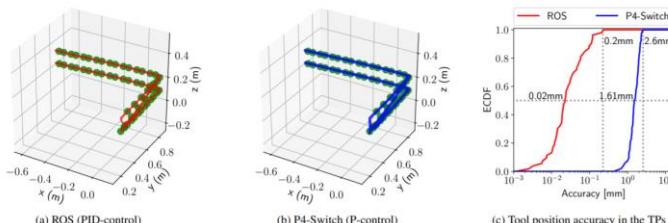
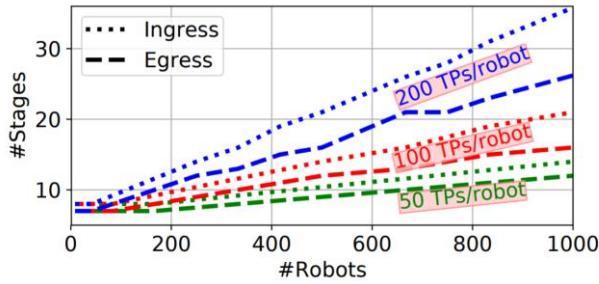
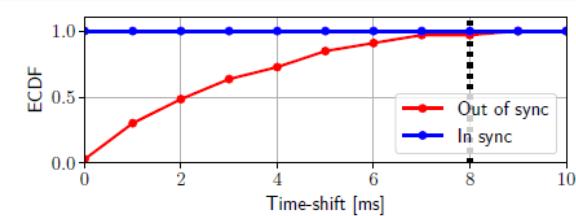
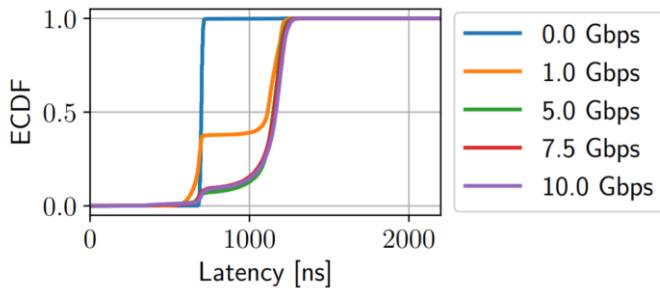
# In-network robot control

- **Silly robots:** set of actuators with UDP-based communication
  - generate a state stream (500 Hz)
  - require velocity commands at 125 Hz
- **P4-switch:** low-level velocity control
  - **low-latency + real-time** requirements
  - responsible for calculating the velocity vectors and sending commands to the robots
- **Industrial controller:** high-level control
  - **running in VM, no real-time requirements**
  - calculating trajectories, etc.



# In-network robot control

- Solves **synchronization** of multiple robots by design
  - Internal clock of the switch
- Good **accuracy** even with our PoC controller
  - At stop position:  $0.5 \times 10^{-7}$  rad  $\sim$  (1m long arm  $\sim$  1-2 micrometer)
- **No strict latency requirements** for the industrial controller
  - **Enabler for cloud robotics**
- Support of **plug-and-play** deployment of new robot arms
- **Scalable** (100s of 6-DoF robot arms with a single switch)
- **Cost factor is feasible**
  - **$\sim$ 10000 USD switch price, 500-1000 robots:  $\sim$ 10-20 USD/robot**
  - Energy cost, etc.
  - DSCs may be even better for this purpose:  **$\sim$ 2000 USD**



# Published journal papers (Q1)

## September 2020 – June 2021

- J. Vestin, A. Kassler, **S. Laki**, G. Pongrácz, [Towards In-Network Event Detection and Filtering for Publish/Subscribe Communication using Programmable Data Planes](#), **IEEE Transactions on Network and Service Management (IEEE TNSM)** journal (Q1, IF: 5.93), Volume: 18, Issue: 1, Page(s): 415 - 428, March 2021, doi: 10.1109/TNSM.2020.3040011
- **S. Laki**, Sz. Nádas, G. Gombos, F. Fejes, P. Hudoba, Z. Turányi, Z. Kiss, Cs. Keszei, [Core-Stateless Forwarding with QoS Revisited: Decoupling Delay and Bandwidth Requirements](#), **IEEE/ACM Transactions on Networking (IEEE/ACM ToN)** journal (Q1, IF: 3.315), vol. 29, no. 2, pp. 503-516, April 2021, doi: 10.1109/TNET.2020.3041235.
- D. Varga, J. M. Szalai-Gindl, B. Formanek, P. Vaderna, L. Dobos and **S. Laki**, [Template Matching for 3D Objects in Large Point Clouds Using DBMS](#), in **IEEE Access** journal (Q1, IF: 3.745), vol. 9, pp. 76894-76907, 2021, doi: 10.1109/ACCESS.2021.3082848.

# Published/Accepted conference papers

## September 2020 – June 2021



- S. Laki et al., TBA, **19th USENIX Symposium on Networked Systems Design and Implementation (NSDI 21 – A\* conf.)**, Accepted full paper
- D. A. AlWahab, G. Gombos, **S. Laki**, On a Deep Q-Network-Based Approach for Active Queue Management, **European Conference on Networks and Communications 2021 (EuCNC'21)**, 8-11 June 2021, Porto, Portugal, Virtual Conference
- Cs. Györgyi, K. Kecskeméti, P. Vörös, G. Szabó, **S. Laki**, In-network Solution for Network Traffic Reduction in Industrial Data Communication, **IEEE International Conference on Network Softwarization (IEEE NetSoft'21)**, 28 June-2 July 2021, Tokyo, Japan, Hybrid On-line Conference
- F. Fejes, Sz. Nádas, G. Gombos, **S. Laki**, A Core-Stateless L4S Scheduler for P4-enabled hardware switches with emulated HQoS [**BEST DEMO AWARD**], **IEEE International Conference on Computer Communications (IEEE InfoCom'21 – A\* conf.)**, 10-13 May 2021, Virtual Conference [Demo paper]
- Dhulfiqar A. AlWahab and **S. Laki**, [ECN-marking with CoDel and its compatibility with different TCP congestion control algorithms](#). In **International Conference on Advanced Science and Engineering 2020 (ICOASE'20)**, 2020, pp. 1-6,  
doi: 10.1109/ICOASE51841.2020.9436575.
- P. Vörös, G. Pongrácz, **S. Laki**, [Towards a Hybrid Next Generation NodeB](#), The **3rd P4 Workshop in Europe (EUROP4 2020)** - co-located with ACM CoNext, Dec 1, 2020 - VIRTUAL CONF.



# Other activities and results

- **Project proposals**

- EU COST Action Proposal  
European Research Network on  
Programmable Networks (ProgNets)

- As main proposer
- Not selected

- H2020 NGI Pointer OC-2 

- Grant for Internet renovators
- P4EDGE project proposal on accessible P4  
programmable edge
- Selected – 200K EUR, 12 month

- OTKA FK\_21

- Theoretical foundations of an expert system  
for programmable data planes
- Joint submission with Máté Tejfel

- **Two TechTalks at P4 Workshop 2021**

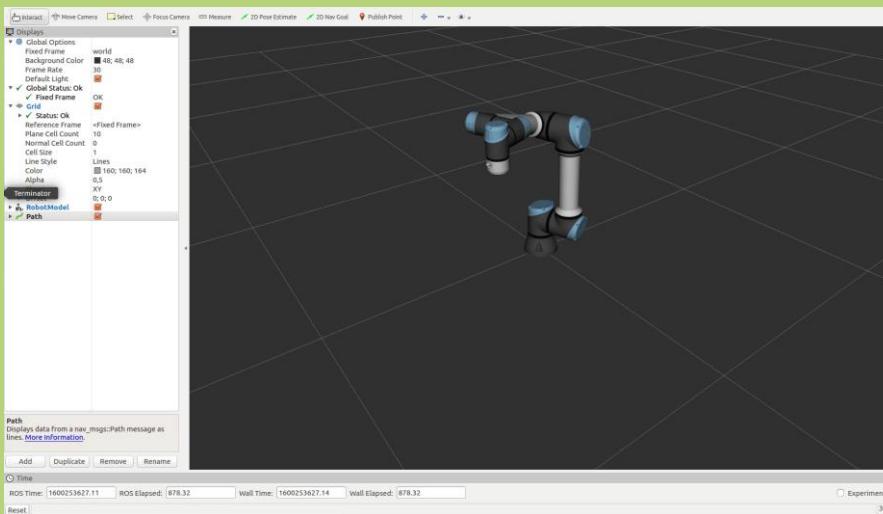


- **New project with ONF P4 Edu. WG**

- P4PI: P4 on Raspberry Pi for Networking Education
  - Collaborators: Noa Zilberman (Oxford) and Robert Soulé (Yale)

- **Accepted P4PI Hackathon at ACM SIGCOMM conference (A\* conf.)**





# Q&A

WEB: [HTTP://LAKIS.WEB.ELTE.HU](http://lakis.web.elte.hu)

Az Alkalmazásiterület-specifikus nagy megbízhatóságú informatikai megoldások című projekt a Nemzeti Kutatási Fejlesztési és Innovációs Alapból biztosított támogatással, a Tématerületi kiválósági program (TKP2020-NKA-06, Nemzeti Kihívások Alprogram) finanszírozásában valósult meg.



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